





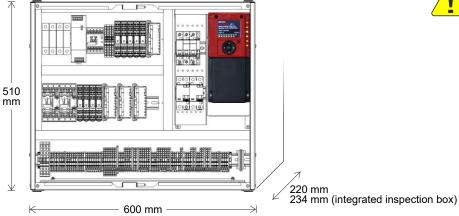
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#### **JUNIOR 4.0 - ELECTRIC SYSTEM FOR HOMELIFTS**



M 230 V (≤ 32A) / 400 V (≤ 16A)

္ကြံ့ 600x510x220 mm

~ 25 kg

✓ Single Phase / Three Phase

√ 7 stops maximum

EN 81-41





#### **SAFETY NOTES**

#### Installation

The control panel must be installed internally with a degree of pollution of not more than 2.

The cabinet has an IP2X degree of protection.

The controller setup and maintenance has to be made by qualified technicians after having carefully read the documentations and electrical schemes provided with the controller.

Protection toward indirect contacts has to be realized through magnetothermic and differential switches and a grounding system. Unless otherwise specified, the customer is requested to provide these protections.

Please refer to the wiring diagram supplied with the control panel for the following protection circuits:

- magnetotermic protection of the motor circuit
- magnetotermic protection of the safety circuit
- protection fuses of all other circuits

Protection measures against electric shock:

- The control panel case of the is metallic and must be grounded as indicated in the circuit diagram supplied with the control panel.
- The command and control circuits (24V) are galvanically separated from the main power supply as indicated in the wiring diagram supplied with the control panel.

#### Maintenance

For control panel's maintenance, please refer to the manual supplied with the control panel. During periodic inspections of the system, check the alarm circuits' battery status of the and the floor return circuit (if present).

Refer to the packaging instructions to handle and move the control panel.

#### 7-SEC SAFETY MODULE

#### Description

SECU.24 module is an electronic device installed in DMG lift control panel that allows to check the status of 7 point of the safety chain of the lift.

The main function of this module is to guarantee galvanic isolation between the safety circuit and the electronic circuits of the control panel.

There is only one version of this module available:

- SECU.24 for control panel with safety circuit powered at 24 V DC [-15/+10%]

#### Installation

The SECU.24 module is supplied by DMG already installed and connected in the control panel. No intervention by the installer is required during commissioning of the control panel.

The common of the connections to the electric safety chain is traced on the printed circuit board in such way, that the common to the contactors or relay-contactors will switch off at interruption of the common (CBC(1)/CBC(9)).

#### Working conditions

The SEČU.24 module is installed in a metal earthed cabinet with minimum IP20 protection and fixed on a DIN rail at following service condition:

- Indoor Use.
- Temperature: -5°C / +40°C
- Relative Humidity: must not exceed 50% at a max temperature of  $+40^{\circ}$ C; may increase at lower temperatures, for example, can be 90% at 20°C.

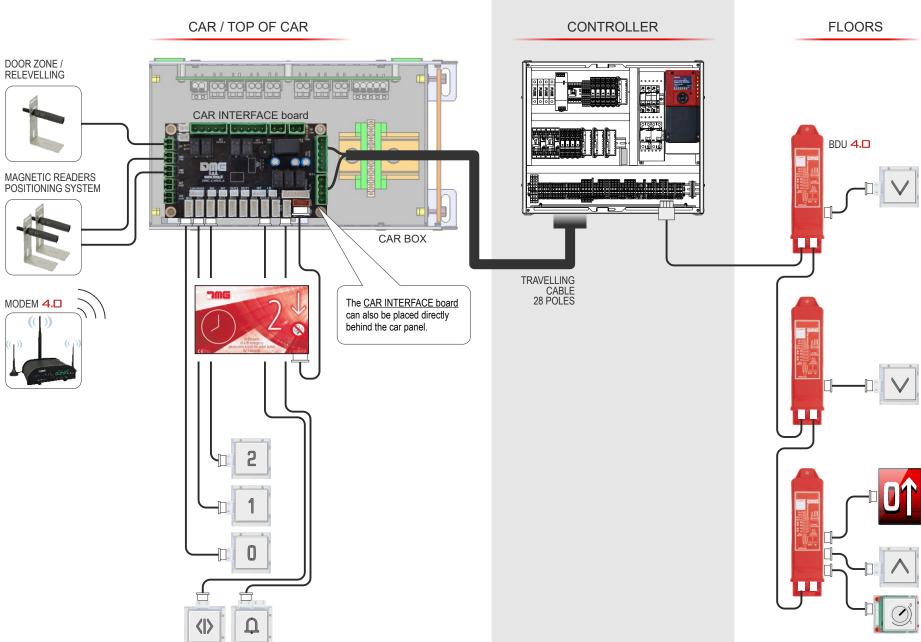
#### Maintenance

In the event of a fault, the device must be replaced, it must not be opened or repaired.



# JUNIOR 4.0

#### **SYSTEM LAYOUT**





# **JUNIOR** 4.0

#### **SYSTEM COMPONENTS**

#### **TOP OF CAR**

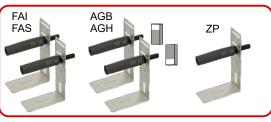




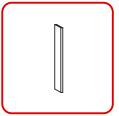
QJ4.CTBOXS CAR box



QJ4.C28CS Travelling cable kit (x m)



QJ4.CTKIMP.H5 / QJ4.CTKIMP.H4 (without AGH) Magnetic readers positioning system + door zone/relevelling + top/bottom reset proximity switches and reset magnets



QJ4.SHCAL100 1 magnet QJ4.KSHCAL

1 x 200mm

4 x 150 mm



QJ4.CTPS Top of cabin stop



**IIII** QJ4.CTPM Inspection box



QJ4.CTPSTISP Inspection box + Stop

#### CAR

**SHAFT** 



**IIII** QJ0.CTSTI



Car INTERFACE board + 7-SEC board



QJ4.SHEX1/2 Final limit switch kit



QJ4.SHP\_/QJ4.SHC\_ Safety chain (doors / pit)



QJ4.SHPSH Pit stop



C40.BDU Floor interface (BDU)



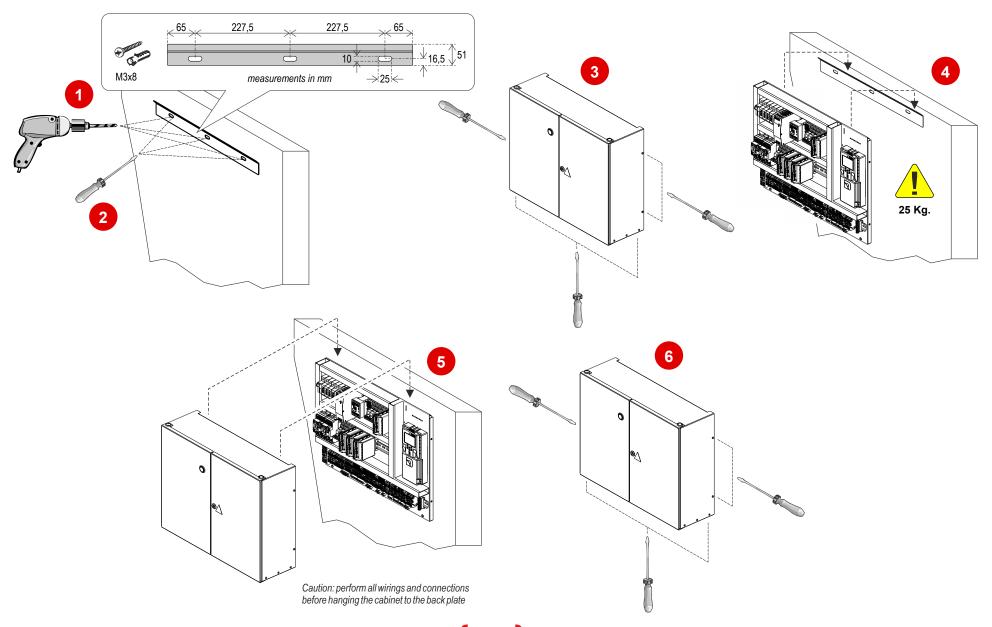
**|||||** QJ4.SHLED\_F05 / F15 + QJ4.SHLED V Shaft illumination kit (5 / 15 m)





# PHASE 0 - INSTALLATION OF BASE ELEMENTS

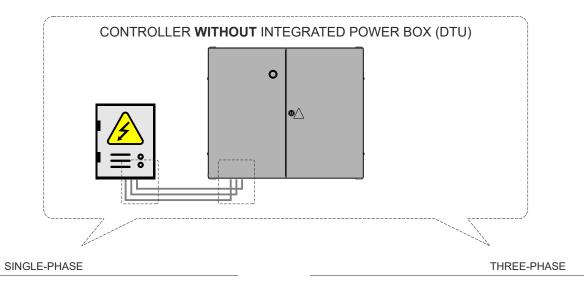
#### **INSTALLING THE CONTROLLER**

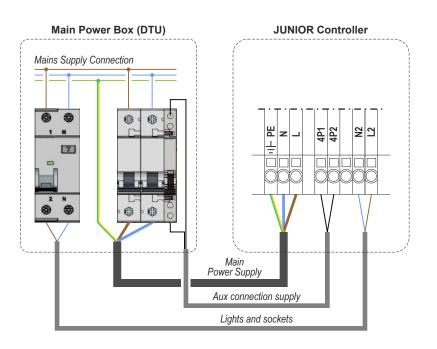


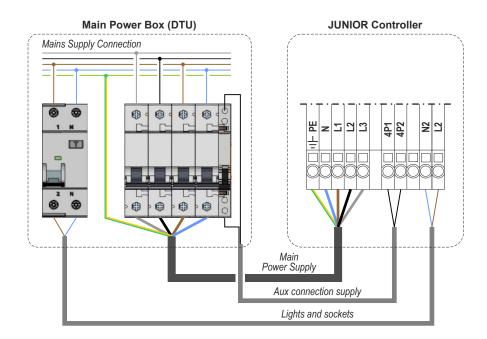




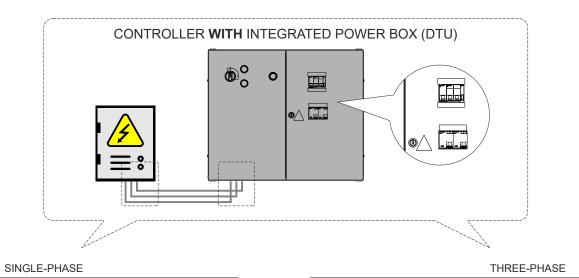
#### **CONNECTING THE MAIN POWER SUPPLY**

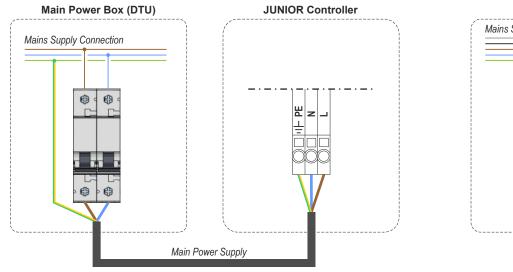


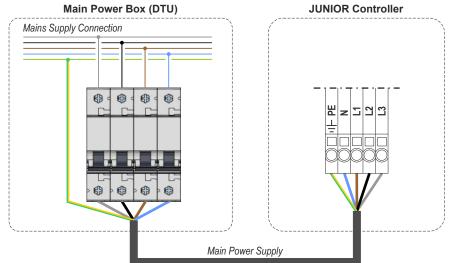








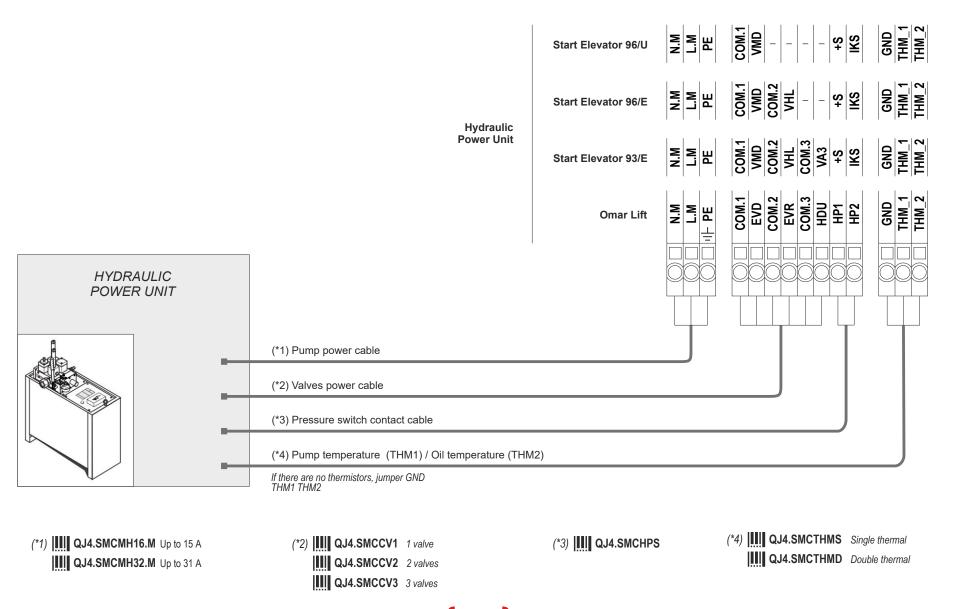








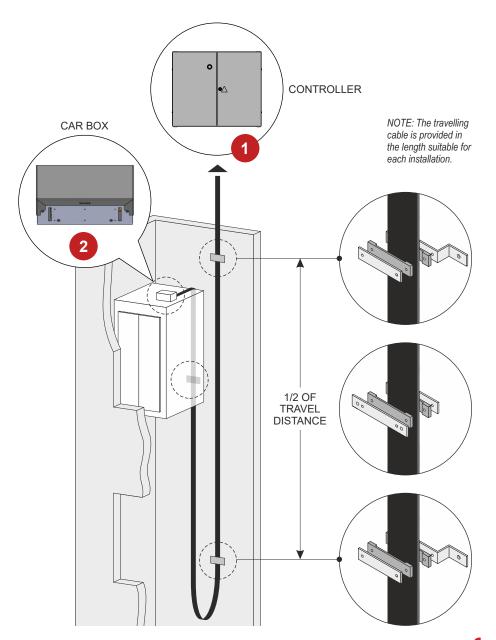
#### **CONNECTING MOTOR OUTPUTS**



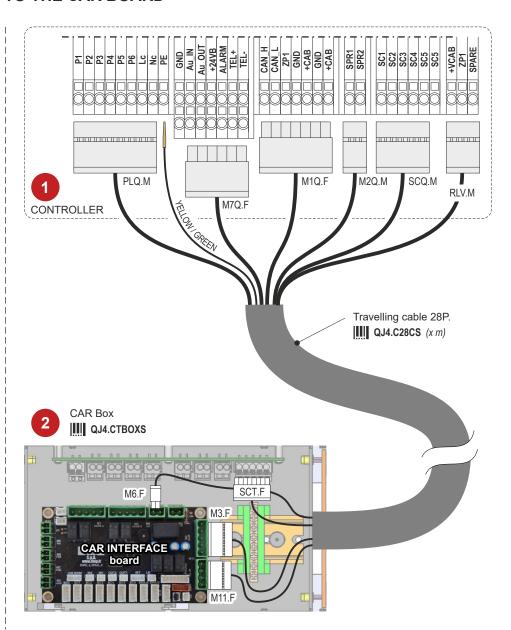




#### **FIXING THE TRAVELLING CABLE**



# CONNECTING THE TRAVELLING CABLE TO THE CAR BOARD



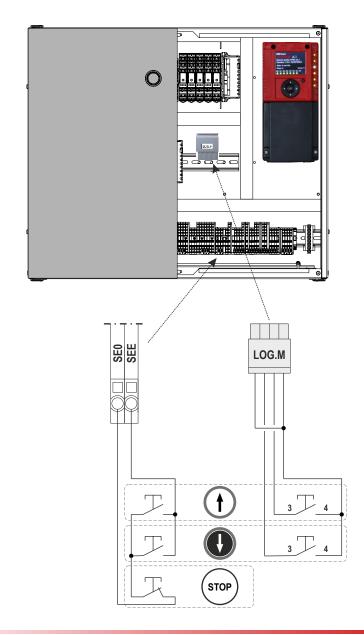


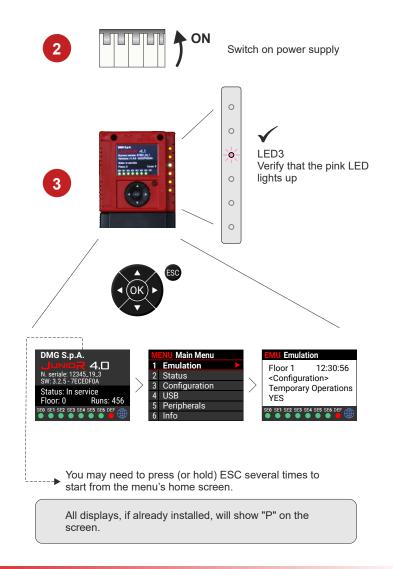


## PHASE 1 - TEMPORARY MODE & ELECTRICAL CONNECTIONS

#### **TEMPORARY OPERATIONS**





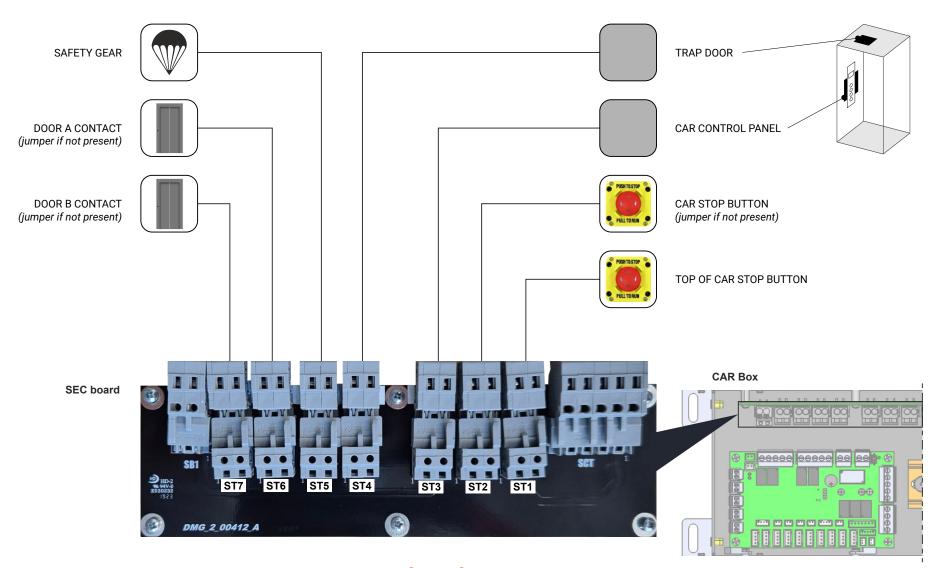






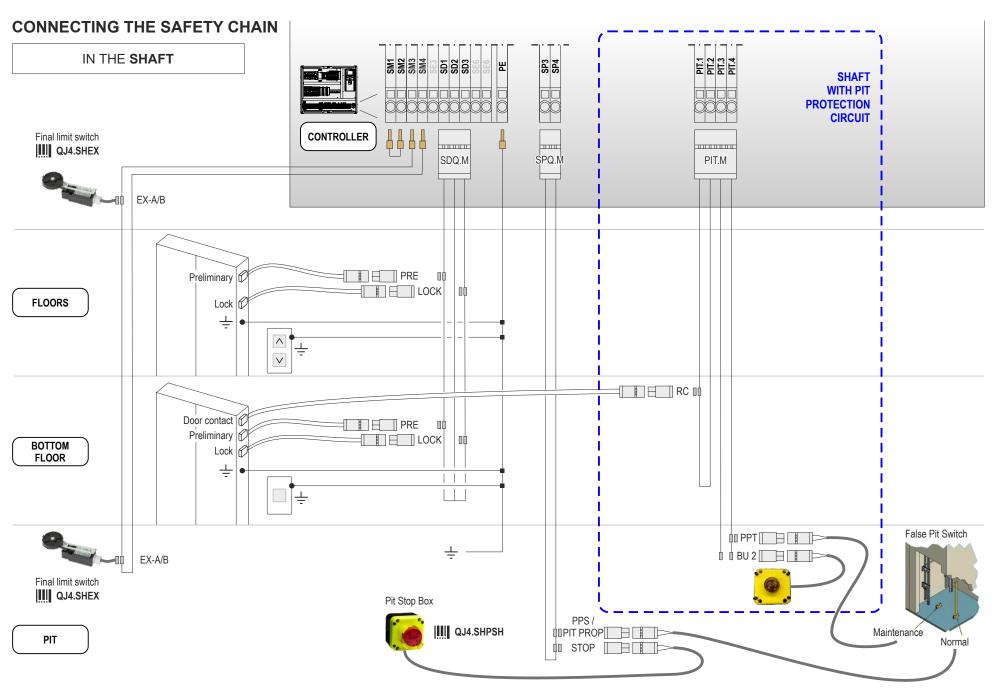
#### **CONNECTING THE SAFETY CHAIN**

IN THE CAR







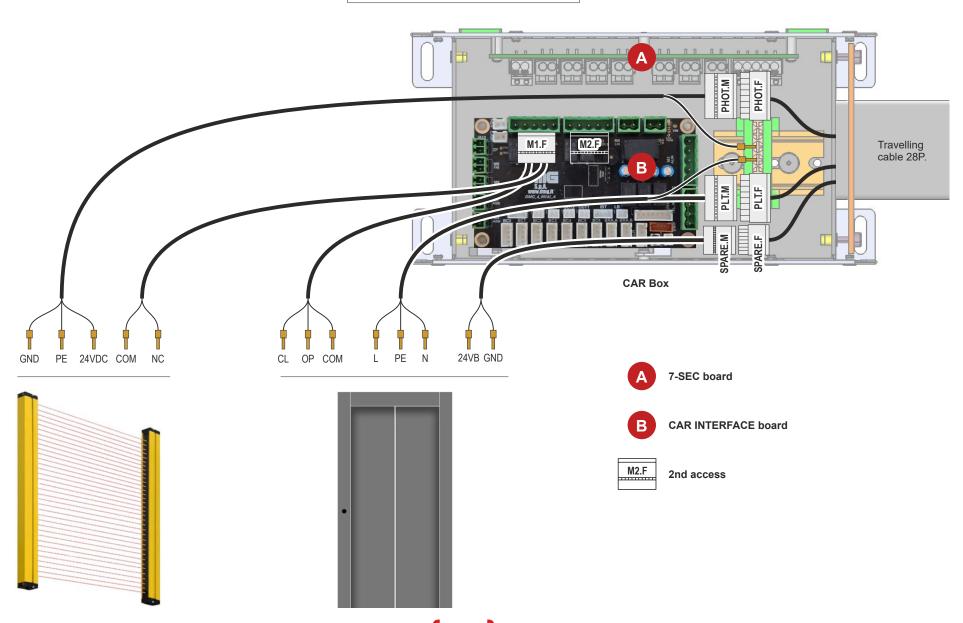






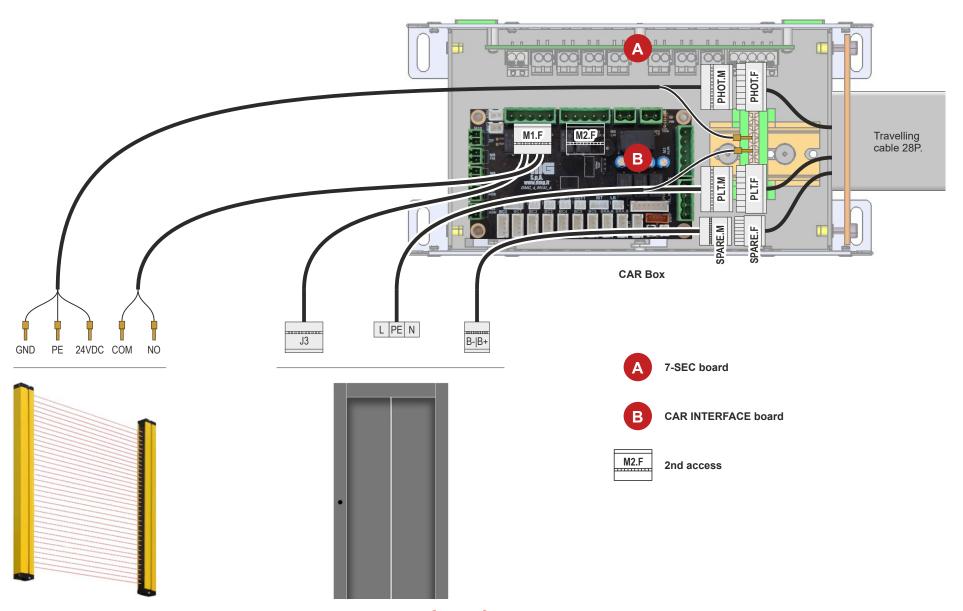
## **CONNECTING CAR DOORS OPERATOR**

**AUTOMATIC** 





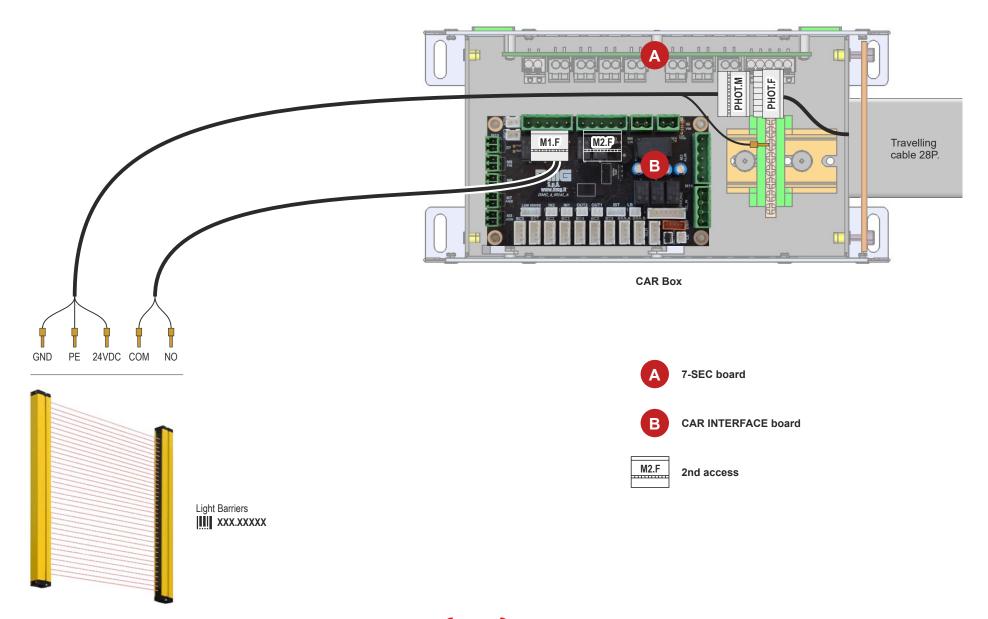
PRISMA AUTOMATIC







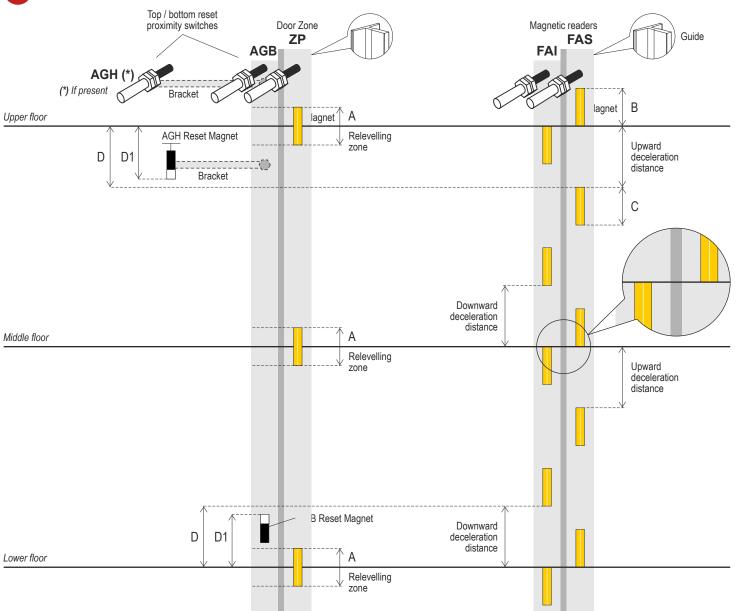
## **CONNECTING LIGHT BARRIERS (NO CAR DOORS)**





#### **CAR POSITION READING SYSTEM**

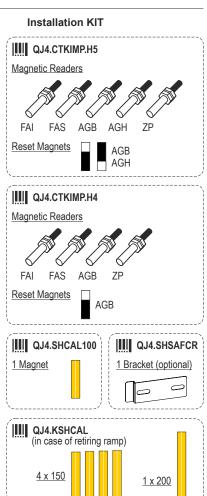






The deceleration magnets (C) can be shortened if necessary.

Lengths (mm) A = 100 B = 100 C = 100	Lengths retiring of A = 100 B = 100 C = 100	(with fixed eam)
Speed (m/s)	D (mm)	D1 (mm)
0,15	250	D-20
0,30	400	D-20

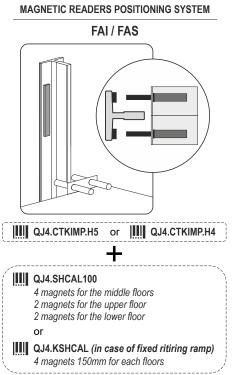


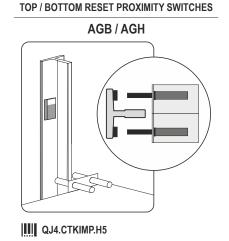


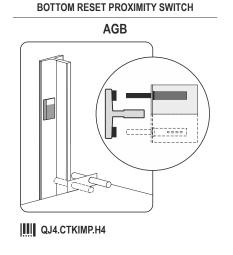


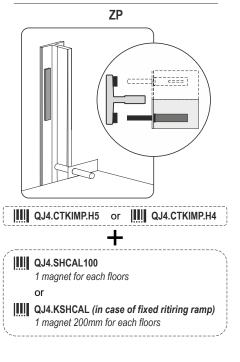
DOOR ZONE / RELEVELLING

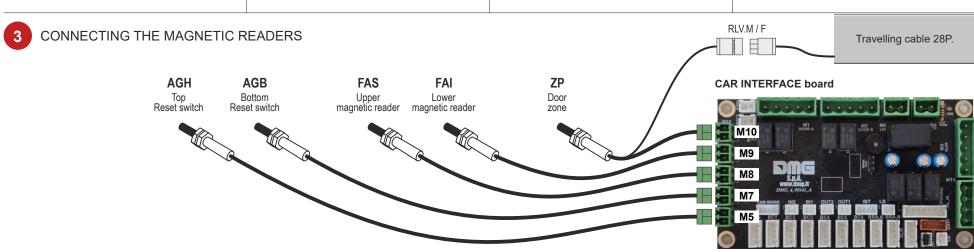
# 2 INSTALLING MAGNETS AND MAGNETIC READERS









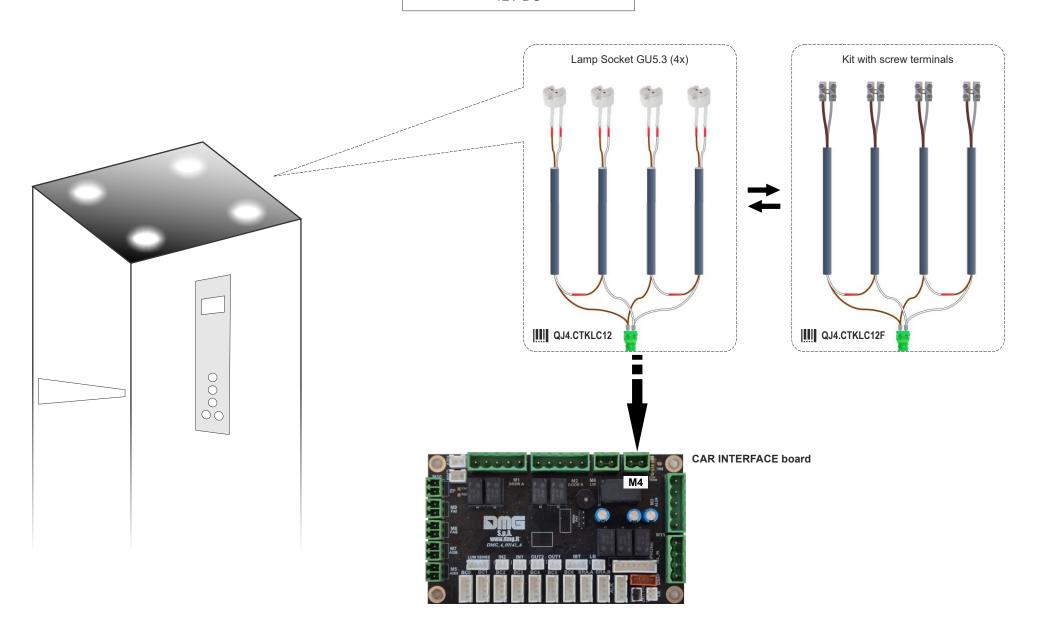






#### **CONNECTING THE CAR ILLUMINATION**

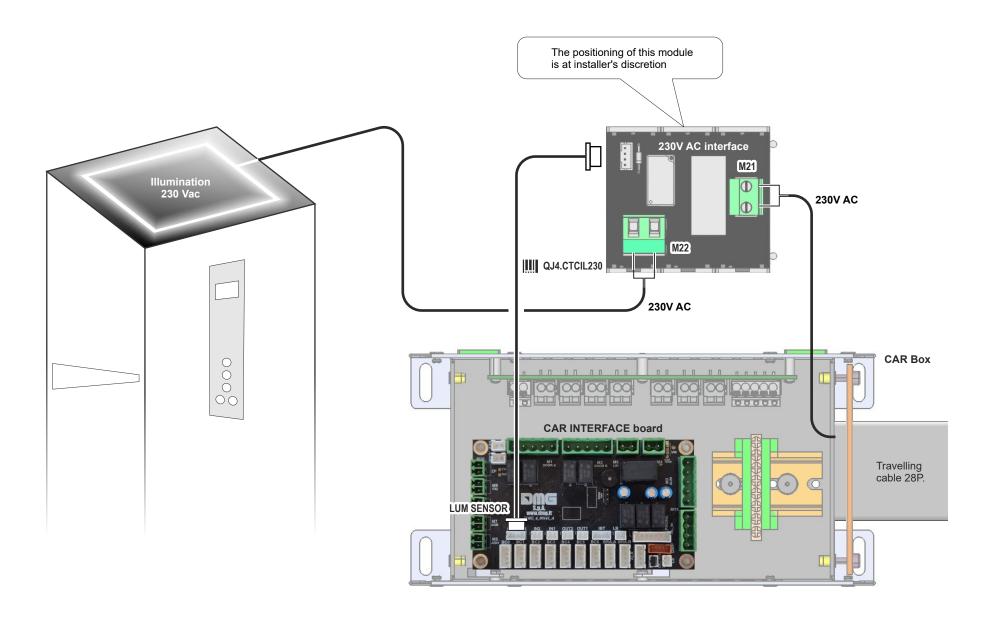
12V DC







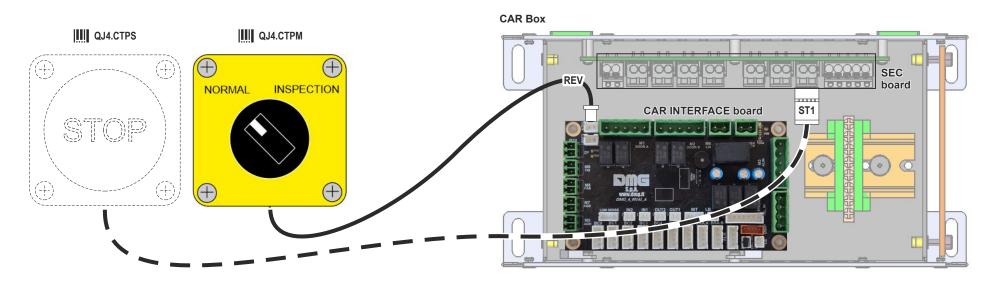
230V AC

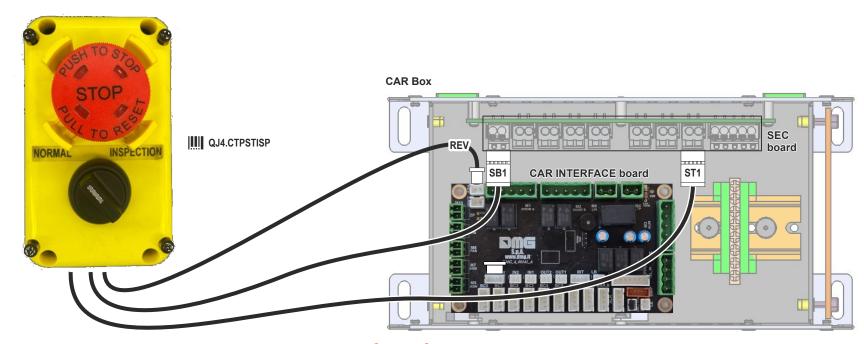






#### **CONNECTING THE INSPECTION BOX**

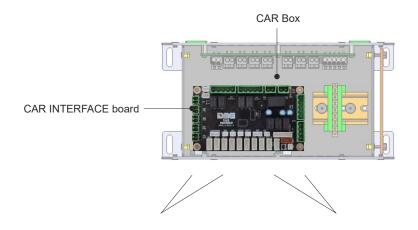




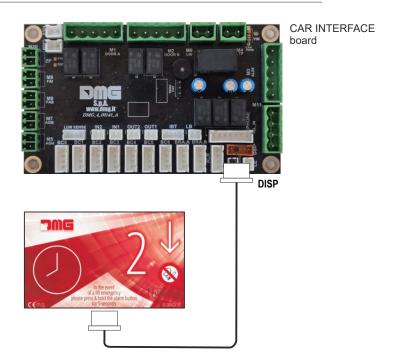




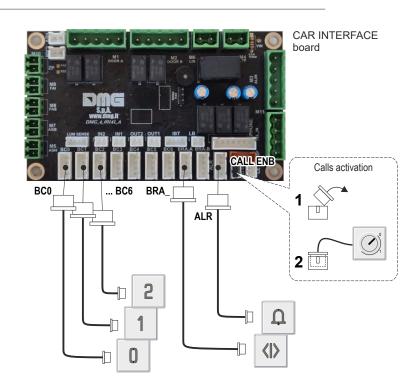
#### **INSTALLING THE CAR PANEL**



#### **DISPLAY & INDICATORS**



#### **CALL / SERVICE BUTTONS**

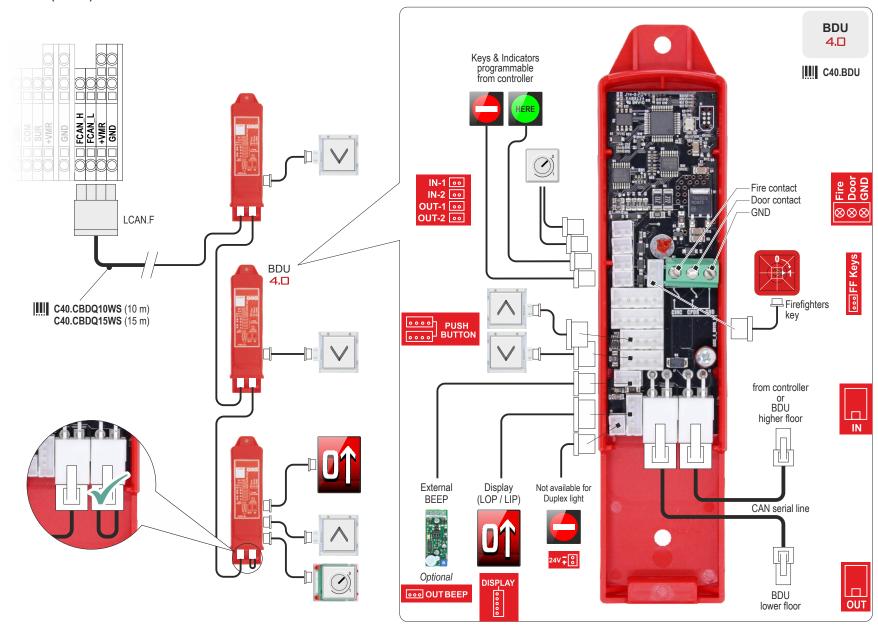






#### **INSTALLING THE FLOOR PANELS**

Floor serial interface (BDU)







#### **BDU PROGRAMMING**



#### **INPUTS**







IN-1 - Call disabling (active input closed).

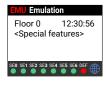
Out of service floor) standing with doors closed.

Default settings



IN-2 - Key input out of service - The system does not accept new calls, cancels the calls at the floors, and

completes the calls already registered in the car, then parks at the programmed floor (Menu <Special features> -









▼ Baggage (if the parameter <Signals> - Ship Functions of the controller is active)

#### **OUTPUTS**



OUT-2 ••



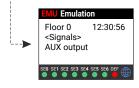
















Do not modify





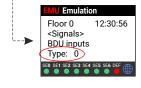
choose

a setting

for each floor



Do not modify

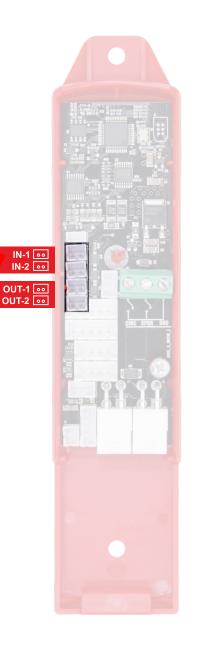




	OUT 1	OUT 2
Type 0	HERE	
Type 1		_
Type 2	HERE	COMING
Type 3	HERE	3 wires display





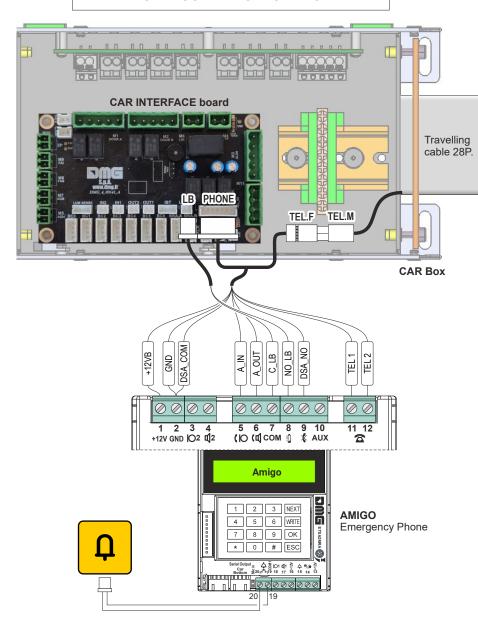




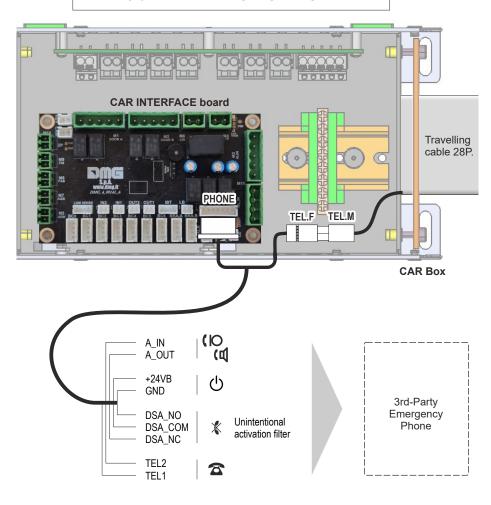
# JUNIOR 4.0

#### **INSTALLING THE EMERGENCY PHONE**

#### **DMG AMIGO EMERGENCY PHONE**



#### **3rd-PARTY** EMERGENCY PHONE

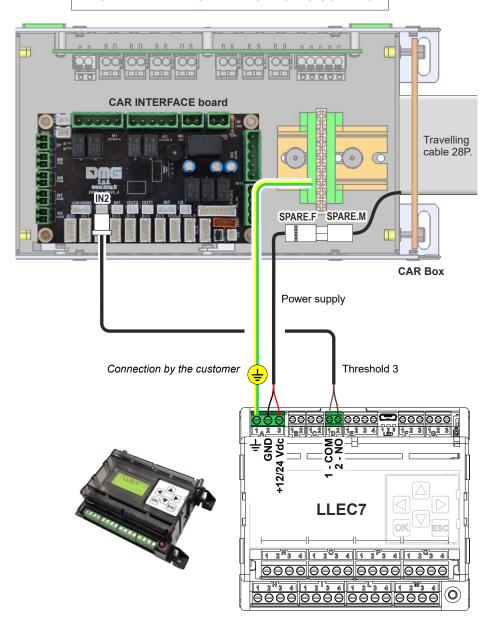




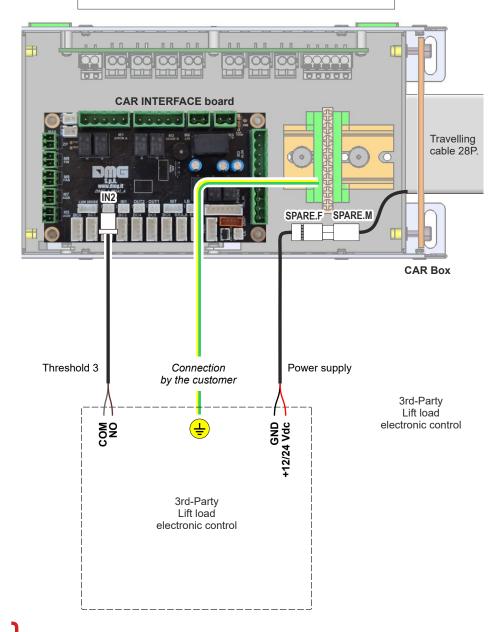


#### INSTALLING THE LLEC7 LIFT LOAD ELECTRONIC CONTROL DEVICE

**DMG LLEC7** LIFT LOAD ELECTRONIC CONTROL



#### 3rd-PARTY LIFT LOAD ELECTRONIC CONTROL







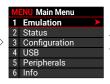
## **PHASE 2** - NORMAL MODE & SYSTEM ADJUSTMENTS

#### SWITCH TO NORMAL SERVICE MODE



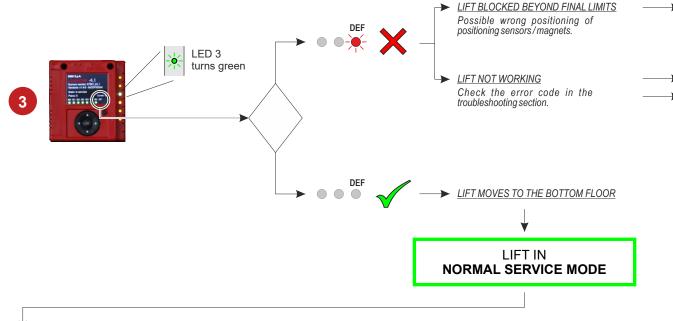






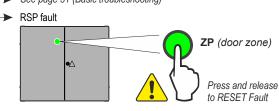


2 Disconnect the temporary operations box



See pages 18 and 19 (Car position reading system) and repeat steps (1) to (3)

➤ See page 31 (Basic troubleshooting)



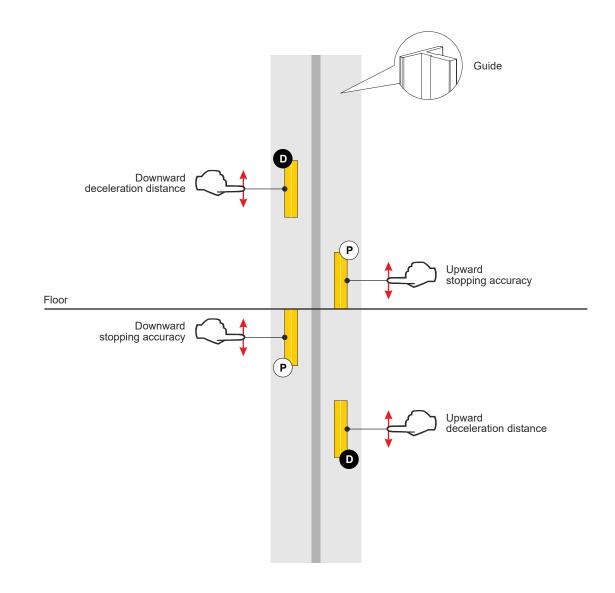
- Set the stopping accuracy (Fine tuning) at each floor See next page
- Perform final system test (check all lift functions)





#### ADJUSTING FLOOR STOPPING ACCURACY

- Read the gap between floor level and car floor edge.
- Move P magnets in the shaft to adjust the stopping position.
- Move D magnets to adjust the deceleration distance.







## CONNECTIVITY (FUSION APP)



Before even seeing how to connect and interact with the installed device, you need to access the Fusion Dashboard cloud software. https://fusiondashboard.dmg.it/dashboard









https://dido.dmg.it/knowledge-base/connectivity-fusion-app/

#### **Connection mode**

W-Fi connectivity to smartphones comes as a standard for all Junior 4.0 controllers, at no extra costs. To enable connectivity and benefits from the advantage of real-time monitoring of the lift, two solutions are available:

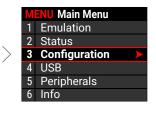


#### LOCAL connections

The local connection carry out on the installation site of the Pitagora system, via Wi-Fi HotSpot located in the TOC board and in the Junior 4.0.

Before connecting locally to the TOC and Playpad 4.0 devices via the Fusion app (described below), it is necessary to check that the Wi-Fi signal is enabled on these 2 devices.











#### **REMOTE connections**

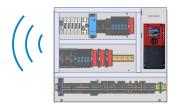
The remote connection allows you to access the devices connected via Telemaco II 4G modem.

Telemaco II 4G is supplied without a SIM; the choice of the SIM is at discretion of the customer.

Instructions for installing the Telemaco II 4G modem:

https://dido.dmg.it/knowledge-base/telemaco-modem-4g-new/





Junior 4.0





#### Lift controller management via the Fusion app

**₽**#

Fusion is the application (IOS / Android) created by DMG for the direct management of compatible installed devices.

Download the Fusion app using the QR code on the side.















Start the FUSION app and login when the smartphone is still connected to internet.

You can reach devices locally without logging in (Select "Local Connection").





Select the type of device to manage.

#### Local connection



Make sure you are connected to the controller's Wi-Fi network:

In the network settings of the smartphone, search and select the Wi-Fi network of the device to connect to (Playpad / TOC):

- DMG\_PLP\_xxx > PLAYPAD
- DMG TOC xxx > TOC

The login credentials are provided by DMG together with the documentation supplied with the product. Finally search for devices (press "Scan") and select the device to manage.

# WiFi PLAYPAD WiFi SSID DMG\_PLP\_11776\_22\_1 WiFi Key xJyn5vzroe WiFi TOC WiFi SSID DMG\_TOC\_11776\_22\_1 WiFi Key glhp2e&\_:1

#### Remote connection



You can now choose the device to manage from either a device list or a device map.









#### **TEST AND MEASUREMENTS**

#### **FINAL LIMIT SWITCH TEST**

#### **RE-LEVELLING TEST**

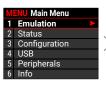


The main switch of the controller must be switched off at every maintenance and at least 365 days after the last switch off and on.

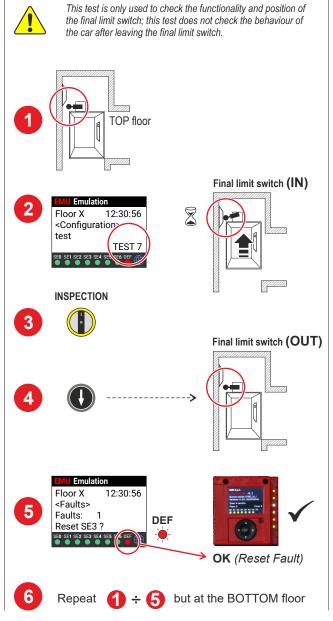
To access the TESTS AND MEASUREMENTS section on the Playpad, set the display as indicated.



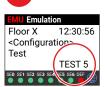


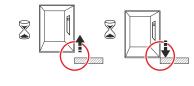


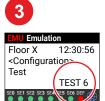


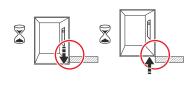














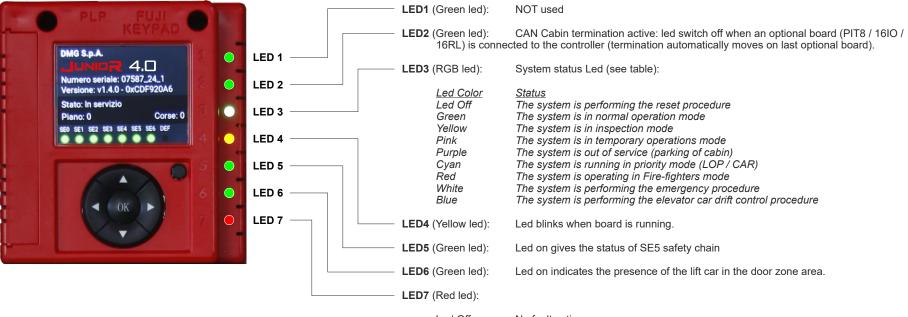




#### BASIC TROUBLESHOOTING

Follow this first-level procedure to detect and remove the most common faults:

# 1 Check Diagnostic LEDs (VVVF unit)



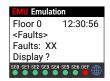
Led Off No fault active

Led Flashing One (or more) fault active Led On Locking fault active

# Read error messages on the PlayPad error menu / Fusion error page









- Error X of XX total.
- Code/description error.
- Car position when the fault was detected.
- · Number of repetitions of the same error.
- Additional code.
- · Date and time of last detection.
- . (\*) If the error is still active.

This Menu lists the last faults stored into the internal memory of the controller. All faults are described in the <a href="Troubleshooting guide.">Troubleshooting guide.</a>. See leaflet on the back of this guide.

WARNING: In case of black out, the internal memory is saved only if the battery is connected.

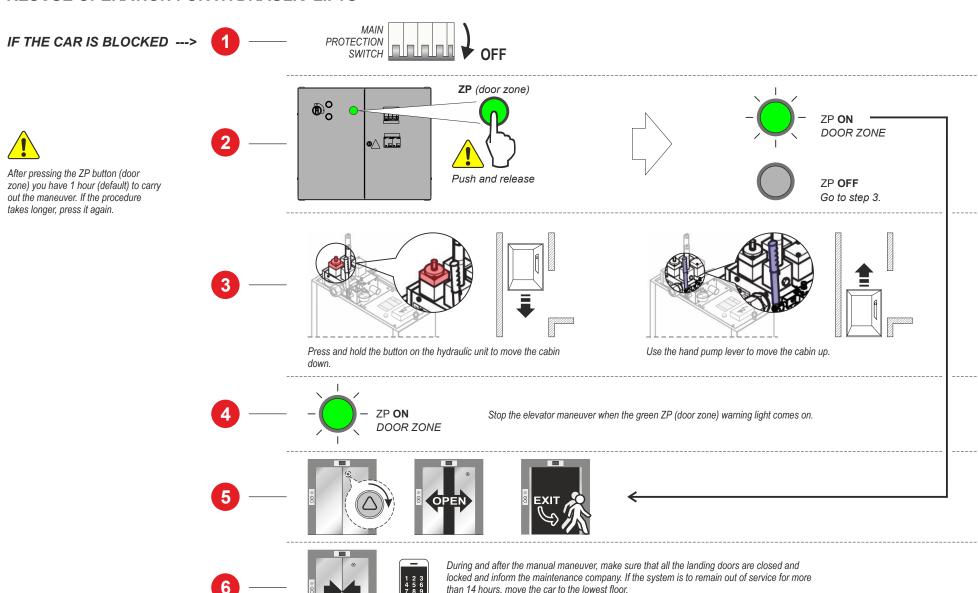
3 If the car is blocked with people inside

Perform the RESCUE OPERATION as shown on the following page ----->>>





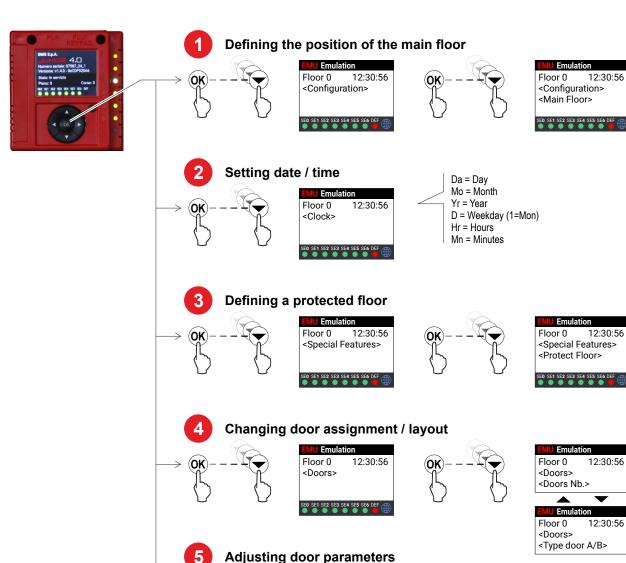
#### **RESCUE OPERATION FOR HYDRAULIC LIFTS**







#### **ADVANCED SETTINGS**



U Emulation

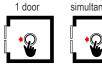
12:30:56

Floor 0

<Doors>

- All calls below this floor are served only upwards (only down collective).
- Lift not in use goes to Main Floor after xx seconds (this parameter can be set in the menu "Special features > Automatic return")

If a protected floor is programmed, when the elevator car reaches the floor, the door does not open, instead the monitor will show images coming from the camera corresponding to that floor. Doors can be opened only by pressing the OPEN DOOR button; if this does not happen, the lift moves to the previous floor and then stops the protected floor mode (this operating mode is only possible with DMG's monitoring system).



2 doors simultaneous

2 doors selective

- Manual doors at floors / car doors manual or not present.
- · Manual doors at floors / car doors independent.
- · Manual doors at floors / car doors automatic.
- · Automatic doors at floors and in the car.

In the "Doors" menu it is possible to manage other parameters such as:

- · Time before activation of the retiring ramp and the lock fault
- · Time before door opening
- · Life car parking time with open doors
- Time before door closes in case of registered calls
- · Many other settings

Emulation

12:30:56

Floor 0

<Doors>



**JUNIOR** 4.0

